

Absolute Encoders - Singleturn



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1) Not applicable with connection types 1 and 2

1) Resolution, preset value and counting direction factory-programmable

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Standard ATEX, optical

Sendix 7053 (Shaft)

SSI interface

SSI / BiSS-C

Technical data

Explosion protection ATEX	
EC type-examination certificate	PTB09 ATEX 1106 X
Category (gas)	🐼 II 2 G Ex d IIC T4 - T6 Gb
Category (dust)	🚯 II 2D Ex tb IIIC T135°C - T85°C Db IP6x
Directive 94/9/EC	EN 60079-0: 2009; EN 60079-1: 2007; EN 60079-31: 2009

Explosion protection IECEx	
Certificate of Conformity (CoC)	IECEx PTB 13.0026 X
Category (gas)	Ex d IIC T4 - T6 Gb
Category (dust)	Ex tb IIIC T135°C - T85°C Db IP6x
IECEx	IEC 60079-0:2007;
	IEC 60079-1:2007; IEC 60079-31:2008

Mechanical characteristics	
Max. speed	6 000 min ⁻¹ (continuous)
Starting torque - at 20°C [68°F]	< 0.05 Nm
Moment of inertia	4.0 x 10 ⁻⁶ kgm ²
Load capacity of shaft radial axial	80 N 40 N
Weight	approx. 1.3 kg [45.86 oz]
Protection acc. to EN 60529	IP67
Working temperature range	-40°C +60°C [-40 +140°F]
Material shaft flange / housing cable	stainless steel seawater-resistant Al, type AlSiMgMn (EN AW-6082) (stainless steel on request) PUR
Shock resistance acc. EN 60068-2-27	2500 m/s², 6 ms
Vibration resistance acc. EN 60068-2-6	100 m/s ² , 55 2000 Hz

Electrical characteristics	
Power supply	10 30 V DC
Current consumption (no load)	max. 45 mA
Reverse polarity protection for power supply (+V)	yes
Short-circuit proof outputs	yes ¹⁾
CE compliant acc. to	EMC guideline 2004/108/EC ATEX guideline 94/9/EC
RoHS compliant acc. to	guideline 2002/95/EC

DIR input

A High signal switches the direction of rotation from the default CW to CCW. The reverse function can also be factory-programmed.

If DIR is reversed when the device is already switched on, this will be interpreted as an error. The status output switches to LOW.

Power-ON delay

After Power-ON, the device requires a time of approximately 150 ms before valid data can be read.

Short-circuit with 0 V or output, only one channel at a time, power supply correctly applied
Other options on request

Sol Internace						
Output driver		RS485 Transceiver type				
Permissible load/channel		max. 20 mA				
Signal level HIGH LOW at I _{Load} = 20 mA		typ 3.8 V typ 1.3 V				
Singleturn resolution	n	1014 bit and 17 bit ²⁾				
Number of revolution	ns	4096 (12 bit)				
Code		Binary or Gray				
SSI clock rate	resolution \leq 14 bit resolution \geq 15 bit	50 kHz 2 MHz 50 kHz 125 kHz				
Monoflop time		< 15 µs ²⁾				
Note: If clock starts cycling within monoflop time a second data transfer starts with the same data. If clock starts cycling after monoflop time, the data transfer starts with updated values. The update rate depends on clock speed, data length and monoflop time.						
Duta lenesii lute	resolution \ge 15 bit	< 4 μs				
Status and parity bit		on request				
BiSS-C interface						
Singleturn resolution	n	10 14 bit and 17 bit ²⁾				
Code		Binary				
Clock rate		up to 10 MHz				
Max. update rate		$<$ 10 $\mu s,$ depends on the clock rate and the data length				
Data refresh rate		≤ 1 µs				
Note: – Bidi	rectional, factory pro plution, code, directio	ogrammable parameters are: on, alarms and warnings				

CRC data verification

SET input					
Input	HIGH active				
Input type		Comparator			
Signal level (+V = Power supply)	HIGH LOW	min. 60 % of +V max. +V max. 25 % of +V			
Input current		< 0.5 mA			
Min. pulse duration (SET)	10 ms				
Timeout after SET signal	14 ms				
Response time (DIR input)	1 ms				

The encoder can be set to zero at any position by means of a HIGH signal on the SET input. Other preset values can be factory-programmed. The SET input has a signal delay time of approximately 1 ms. Once the SET function has been triggered, the encoder requires an internal processing time of approximately 15 ms before the new position data can be read.

Status output		
Output driver		Open Collector, internal pull-up resistor 22 kOhm
Permissible load		max. 20 mA
Signal level	HIGH	+V < 1 V
Activo at	2011	
ACTIVE at		LOW

The status output serves to display various alarm or error messages. The status output is HIGH (Open Collector with internal pull-up 22k) in normal operation.



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Terminal assignment

Interface	Type of connection	Features	Cable (isolate	Cable (isolate unused wires individually before initial start-up)											
			Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Stat	Ŧ		
2	1, 2, A, B	SET, DIR	Cable marking:	1	2	3	4	5	6	7	8	9	YE/GN	shield	

+V: Encoder power supply +V DC

- 0 V: Encoder power supply ground GND (0 V)
- C+, C-: Clock signal

D+, D-: Data signal

Set input. The current position becomes defined as position zero. SET:

Dimensions

Dimensions in mm [inch]

Clamping-synchronous flange, ø 70 [2.76] Shaft type 1 with axial cable outlet

1 6 x M4, 10 [0.39] deep

2 Keyway for DIN 6885-A-4x4x25 key

DIR:	Direction input: If this input is active, output values are counted
	backwards (decrease) when the shaft is turning clockwise.

Stat: Status output ÷:

Protective earth

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Clamping-synchronous flange, ø 70 [2.76] Shaft type 2 with radial cable outlet

1 6 x M4, 10 [0.39] deep



