Legend	Legend for fold-out page		
Α	Jumper	□ 38	
В	Analog inputs, terminal strip X3.1	₩ 35	
C	Analog outputs, terminal strip X3.2	LLI 35	
D	Digital inputs and outputs, terminal strip X3.3	□ 36	
E	Nameplate	□ 25	



Current documentation and software updates concerning Lenze products can be found on the Internet in the "Services & Downloads" area under

http://www.Lenze.com

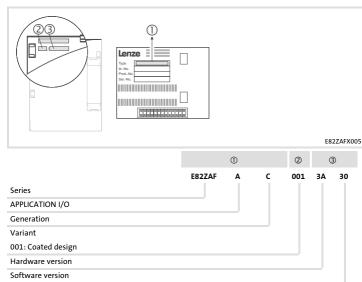
Validity

These instructions are valid for

► E82ZAFAC001, APPLICATION I/O function modules, as of version 3A.30.

These instructions are only valid together with the Operating Instructions for the standard devices permitted for the application.

Identification



Order designation

E82ZAFAC00x3A30

Function

The function module enables the user to control Lenze frequency inverters with analog and digital control signals.

Application range

Can be used with		As of version
Frequency inverter	8200 vector	Vx14
•	8200 motec	Vx14

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i Contents

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Definition of notes used

The following pictographs and signal words are used in this documentation to indicate dangers and important information:

Safety instructions

Structure of safety instructions:



Danger!

(characterises the type and severity of danger)

Note

(describes the danger and gives information about how to prevent dangerous situations)

Pictograph and signal word	Meaning
Danger!	Danger of personal injury through dangerous electrical voltage. Reference to an imminent danger that may result in death or serious personal injury if the corresponding measures are not taken.
Danger!	Danger of personal injury through a general source of danger. Reference to an imminent danger that may result in death or serious personal injury if the corresponding measures are not taken.
Stop!	Danger of property damage. Reference to a possible danger that may result in property damage if the corresponding measures are not taken.

1 Safety instructions Definition of notes used

Application notes

Pictograph and signal word	Meaning
Note!	Important note to ensure troublefree operation
- 🍟 - Tip!	Useful tip for simple handling
(Reference to another documentation

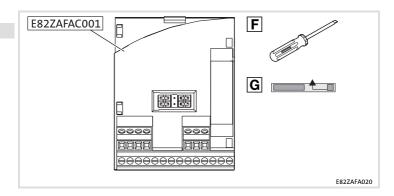
Residual hazards



Danger!

Observe the safety instructions and residual hazards included in the instructions for the standard device.

2 Scope of supply



Pos.	Scope of supply
	E82ZAFAC001 function module
	Mounting Instructions
F	Screwdriver
G	Adhesive tape

Follow the notes given in the Mounting Instructions for the standard device for the mechanical installation of the function module.

The Mounting Instructions for the standard device ...

- ▶ are part of the scope of supply and are enclosed with each device.
- provide tips for avoiding damage through improper handling.
- ▶ describe the obligatory order of installation steps.

4 Electrical installation

Wiring according to EMC

Wiring according to EMC

Please observe the following for wiring according to EMC guidelines:



Note!

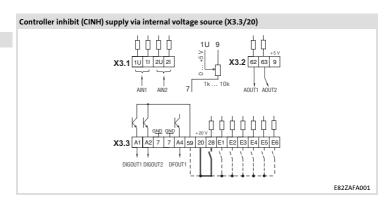
- Separate control cables from motor cables.
- Lead the shields as far as possible to the terminals (unshielded core length < 40 mm).
- Connect control and data cable shields as follows:
 - Analog signal cable shields must be connected with one end at the inverter.
 - Digital signal cable shields must be connected with both ends.
- More information about wiring according to EMC guidelines can be obtained from the corresponding documentation for the standard device.

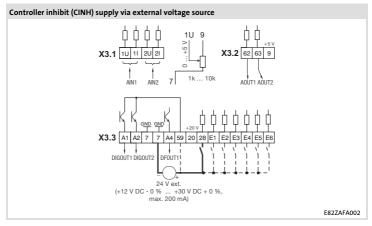
Wiring

Terminal data

Electrical connection	Terminal strip with screw connection
Possible connections	rigid: 1.5 mm² (AWG 16)
	flexible:
	without wire end ferrule 1.0 mm ² (AWG 18)
	with wire end ferrule, without plastic sleeve 0.5 mm ² (AWG 20)
	with wire end ferrule, with plastic sleeve 0.5 mm² (AWG 20)
Tightening torque	0.22 0.25 Nm (1.9 2.2 lb-in)
Bare end	5 mm

4 Electrical installation





Minimum wiring required for operation

(0 ... +12 mA) 0 ... +20 mA 1) +4 ... +20 mA 1)

+5.2 V

X3.1/	Signal type	Function	Level (Lenze setting: in bolt print)
1U/2U	Analog inputs	Actual or setpoint inputs (master voltage) Use jumper and C0034 to change range	0 +5 V 0 +10 V -10 V +10 V
11/21		Actual or setpoint inputs (master current) Use jumper and C0034 to change range	0 +20 mA +4 +20 mA +4 +20 mA (open-circuit monitored)
X3.2/	Signal type	Function	Level (Lenze setting: in bolt print)
62	Analog outputs	Output frequency	Voltage output: 0 +6 V 0 +10 V ¹⁾ Current output:

Motor current

setpoint potentiometer

63

9

Internal, stabilised DC voltage supply for 1) Output level 0 ... + 10 V or 0/+4 ... +20 mA: Adapt offset (C0422) and gain (C0420).

4 Electrical installation

X3.3/	Signal type	Function	Level (Lenze setting: in bolt print)		t)	
A1	Digital outputs	Ready for operation				
A2	outputs	Not prefabricated		0/+20 V at DC internal 0/+24 V at DC external		
7	-	GND, reference potential	-			
A4	Frequency output	DC-bus voltage	HIGH: +18 V +2 LOW: 0 V	+18 V +24 V (HTL)		
59	-	DC supply for X3/A1 and X3/A2	+20 V (into	+20 V (internal, bridge to X3/20)		
			+24 V (external)			
20	-	Internal DC voltage supply for control of digital inputs and outputs	+20 V ± 10	+20 V ± 10 %		
28		Controller inhibit (CINH)	1 = START			
E1 ¹⁾		Activation of JOG frequencies		E1	E2	
		JOG1 = 20 Hz JOG2 = 30 Hz	JOG1	1	0	
E2 ¹⁾		JOG3 = 40 Hz	JOG2	0	1	
			JOG3	1	1	
E3	Digital inputs	DC-injection brake (DCB)	1 = DCB			
E4	1 Imputs	Change of direction of rotation		E4		
		CW/CCW rotation	CW	0		
			CCW	1		
E5	Not prefabricated Not prefabricated		-			
E6			-			

¹⁾ Optional frequency input 0 ... 102.4 kHz (single-tracked or double-tracked), configuration via C0425

Before switching on



Note!

- ► If your configuration differs from the Lenze settings, please read the instructions given under "Individual settings".

 40
- ▶ Please observe
- that the jumpers can only be plugged when the device is switched off.
 - that the jumpers at the function module are set correctly.

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5 Commissioning

Jumper positions for inputs

Jumper positions for inputs

_1	3	5	7	9
•	#6			
	H.		п	4.0
2	4	6	8	10

Lenze setting (bold printing in tables)

- 1 3
- 2-4
- 7-9
- 8 10



Note!

If a setpoint potentiometer is supplied internally via X3.2/9, the jumper must be set between 0 ... +5 V. Otherwise it is not possible to use the whole speed range.

Analog inputs		Possible levels			
		0 +5 V	0 +10 V	-10 +10 V	
X3.1/1U	Jumper	7 - 9: free	7 - 9	7 - 9	
Analog input 1, AIN1	Code	C0034/1 = 0	C0034/1 = 0	C0034/1 = 1	
X3.1/2U	Jumper	8 - 10: free	8 - 10	8 - 10	
Analog input 2, AIN2	Code	C0034/2 = 0	C0034/2 = 0	C0034/2 = 1	

Analog inputs		Possible levels			
		0 +20 mA	+4 +20 mA	+4 +20 mA ¹⁾	
X3.1/1I Analog input 1, AIN1	Jumper	optional	optional	optional	
	Code	C0034/1 = 2	C0034/1 = 3	C0034/1 = 4	
X3.1/2I	Jumper	optional	optional	optional	
Analog input 2, AIN2	Code	C0034/2 = 2	C0034/2 = 3	C0034/2 = 4	

¹⁾ open-circuit monitored

CommissioningJumper positions for outputs

Jumper positions for outputs

_1	3	5	7	9
	Ю			
	Ø			
5	4	6	R	10

Lenze setting (bold printing in tables)

- 1-3
- 2 4
- 7-9
- 8 10

Analog outputs		Possible levels		
		0 +10 V	0 +20 mA	+4 +20 mA
X3.2/62 Analog output 1,	Jumper	1-3	3 - 5	3 - 5
AOUT1	Code	C0424/1 = 0	C0424/1 = 0	C0424/1 = 1
X3.2/63 Analog output 2,	Jumper	2 - 4	4 - 6	4 - 6
AOUT2	Code	C0424/2 = 0	C0424/2 = 0	C0424/2 = 1

5 Commissioning

Commissioning using Lenze settings

Commissioning using Lenze settings

Step	Procedure	Comments	
1.	Switch on the mains voltage.	After approx. 1 second, the controller is ready for operation. Controller inhibit is active. Controller reaction The green LED is blinking. Keypad: ROY ME (if attached)	
2.	Control digital inputs.	Lenze setting CW rotation: E1, E2, E3, E4: LOW CCW rotation: E1, E2, E3: LOW E4: HIGH Individual setting Adapt digital inputs under C0007 or C0410. The digital inputs must be controlled so that the drive can start via terminal after controller enable.	
3.	Select setpoint	Lenze setting Setpoint: 0 +10 V Individual setting Depending on jumper position at module Apply master current to X3.1/11 or X3.1/21 or apply master voltage to X3.1/10 or X3.1/2U Check C0034	
4.	Enable controller via terminal.	Lenze setting X3.3/28 = HIGH (+12 V +30 V) Controller reaction The green LED is on. Keypad: ©© Off	
5.	The drive should be running now.		



Note!

- ► The controller is only ready for operation if a HIGH signal is applied to X3.3/28 (controller enable via terminal).
 - Please observe that the controller can be inhibited through various sources. All sources act like a series connection of switches.
 - If the drive does not start although the controller has been enabled via X3.3/28, check whether the controller has been inhibited through a different source. Another source could be the source for the keypad.



Connection data

X3.1/		
1U/2U 1I/2I	Temperature error (0+60°C) for level (ref. to current value): ■ 0 +5 V: 1 % ■ 0 +10 V: 0.6 % ■ -10 +10 V: 0.6 % ■ 0/+4 +20 mA: 0.6 % Linearity error: ± 0.5 % A/D converter: Resolution: 10 bit, Error (ref. to limit value): 1 digit ≡ 0.1 %	
	Input resistance: Voltage signal: > 50 k Ω , current signal: 250 Ω	
X3.2/		
62 63	Resolution: 10 bit Linearity error (ref. to current value): ± 0.5 % Temperature error (0+60 °C): 0.6 % Load capacity (0+10 V): $I_{max}=2$ mA Load resistance (0/+4+20 mA): ≤ 500 Ω	
9	Load capacity: I _{max} = 5 mA	
X3.3/		
A1 A2	Load capacity: ■ I _{max} = 10 mA, with internal supply ■ I _{max} = 50 mA, with external supply	
A4	Load capacity: I _{max} = 8 mA f = 50 Hz 10 kHz	
20	Load capacity: ΣI_{max} = 60 mA	
28 E1 ¹⁾ E2 ¹⁾	Input resistance: 3.2 k Ω	
E3 E4 E5	1 = HIGH (+12 +30 V), PLC level, HTL 0 = LOW (0 +3 V), PLC level, HTL	
E6		

Optional frequency input 0 ... 102.4 kHz (single or two-track), configuration via C0425

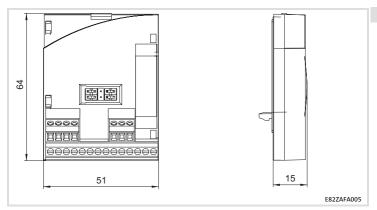
6 Technical data

Operating conditions

Operating conditions

Ambient conditions				
Climatic conditions				
Storag	1 K3 acc. to IEC/EN 60721-3-1	- 25 + 60 °C		
Transpor	t 2 K3 acc. to IEC/EN 60721-3-2	- 25 + 70 °C		
Operatio	3 K3 acc. to IEC/EN 60721-3-3	- 20 + 60 °C		
Degree of pollution	2 acc. to IEC/EN 61800-5-1			
Enclosure	IP20			

Dimensions



All dimensions in mm